

Robotics For Engineers Yoram Koren

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Professor Koren was the Director of the NSF Engineering Research Center for Reconfigurable Manufacturing Systems (ERC-RMS) for 16 years, since he established the Center in 1996 until 2012. The ERC-RMS has created the largest academic manufacturing R&D testbed in the US, which was inaugurated by US Senator Spencer Abraham in October 1998.

Yoram Koren—Home Page for Prof. Yoram Koren---
Yoram Koren is the founding director (in 1996) of the Engineering Research Center (ERC) for Reconfigurable Manufacturing Systems (RMS). The ERC-RMS was the very first NSF-sponsored ERC in the U-M College of Engineering, which is recognized as a formal milestone in the College 150-year history.

Home | Yoram Koren
In 1973, Yoram Koren is featured for his work on Numerical Control and reconfigurable manufacturing.

Yoram Koren | Mechanical Engineering
Robotics for Engineers McGraw-Hill Book Co. New York, 1985 One of the very first books on robotics, regarded by experts as the best introductory book to the robotics topic, still contains the scientific basis of kinematics and controls of robot arms. The book was translated to Japanese and French, and received the Dori Award.

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Robotics For Engineers Yoram Koren Ukyoa
Robotics offers encyclopedic coverage of the control and design of robotic systems, including kinematics, dynamics, soft-computing techniques, and teleoperation. Mechanical systems designers and engineers have few resources dedicated to their particular and often unique problems.

The Mechanical Systems Design Handbook | Taylor & Francis ---
Professor Yoram Koren is internationally recognized for innovative contributions to robotics, flexible automation and reconfigurable manufacturing systems. He is a member of the U.S. National Academy of Engineering, and is credited with concieving of the reconfigurable manufacturing paradigm and as a pioneer in establishing flexible automation, computer numeric control and adaptive control of machine tools as research fields and an educational discipline.

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