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The fantail operates on the error signal $\theta_w - \theta_T$, and as the fantail turns, it drives the turret to turn. $x y$ Wind * * q_W q_T q_F Fantail Turret = Wind angle = Fantail angle = Turret angle q_W q_T q_F Torque q_Tq_W Error - ProcessController Gears & turret Fantail © 2011 Pearson Education, Inc., Upper Saddle River, NJ.

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